Software for Space, Defense & Intelligence Wind Turbine/Radar System Modeling and Analysis

By Gregory Haun, Lead Solutions Architect, AGI

Presented to the Long Island Chapter of the IEEE Antennas & Propagation Society on October 24th, 2013

Agenda



- § AGI overview
- **§ Encroachment and Operational Concerns**
- **§ Modeling Impacts of Renewable Energy**
 - Wind Turbines
 - Solar Reflectors
- **§ Wind/Radar Customized Solutions**
 - AGI Wind/Radar Plugin for Developer
 - DHS WT/RMT
 - NORAD ROEMS

§ Summary

AGI



SPACE

DEFENSE

INTELLIGENCE



- Space Mission design
- Space Operations
- SSA
- Launch Operations
- Conjunction Analysis

- Multi Asset Management
- TMD/BMD
- Battlespace planning
- Mission Planning
- Electronic Warfare

- Mission planning
- C4ISR
- Sensor/Collection planning
- Geospatial Intel

AGI Basics



- COTS software for analysis and visualization
- Models object in space over time
- Analyze and understand relationships
- Constrain relationships
- High fidelity 4D visualization



STK Paradigm





STK Predictive Computation



- § Determine values of, and "constraint" satisfaction time periods that meet mission objectives
 - Geometric
 - Proximity
 - Pointing
 - Lighting
 - Line-of-sight atmospheric conditions
 - Inter-object geometry
 - Comm link quality, Jamming values
 - Radar performance measures
 - Terrain vertical profile
 - GPS DOP and Nav accuracy prediction





STK Capabilities for GIS



§ Maps

- .kml, .shp, .mxd
- geodatabases
- custom GIS (e.g., DAFIF)

§ Models

– COLLADA

§ Imagery

- .ecw, .img, .jp2, .ntf, .sid, .tif
- CADRG, & CIB

§ Terrain

- DTED, DEM, ArcInfo, GTOPO, MOLA, MUSE, GEODAS
- § 2D/3D Visualization



Terrain analysis



§ AzEl Terrain masking (to range, to altitude)

- Colorize flight paths within view of detection mask





Dynamic Geometry Modeling



- **§** Time systems
 - UTCG, LCL, IRIG, GPS, Julian
- § Coordinate Systems
 - ECI, ECF, ENU, NED, Custom
- § Vector geometry tool
 - Points, Vectors, Angles, Planes, Axes
- § Relative position information
 - RIC, AER, Intervisibility, Doppler
- § Celestial
 - Sun, moon, etc.



RF Analysis



- **Dynamics** §
 - Position/Velocity Ú
 - Orientation Ú
- Transmitter/Receiver §
 - Power Ú
 - Frequency Ú
 - Delay Ú
 - Waveform Ú
 - Filtering Ú
- § Antenna
 - Dynamic Gain Ú
 - Polarization Ú
 - Losses Ú

Environment §

- **Terrain (TIREM)** ú
- Absorption and refraction Ú
- lonosphere Ú
- Obscuration and Diffraction (terrain, objects, etc.) Weather models Ú
- Ú
- **Visualization** §
 - Coverage Ú
 - Antenna Gain Volumes Ú







RF Environmental Effects



- § Rain, Gaseous Absorption, Cloud/Fog, Tropospheric
- § Terrain diffraction with TIREM
- § Urban environment modeling (REMCOM Wireless Insite RT)
- § Plugin points for external RF models



Communications Link Modeling





Horizontal Polarization



C/N Plot – Horiz & Vert



Ground Omni





Vertical Polarization



Urban communications



§ Assess signals in urban environments

§ Analyze loss using multiple paths

§ Site specific





Computations consider three diffracted paths to receiver

1

Radar



§ Types

- Mono-static
- Bi-static
- SAR

§ Power

- Peak
- Losses
- Antenna

§ Operating Modes

- § Search/Track
 - Fixed PRF
 - Continuous

§ Filters

§ Detection

- SNR
- Aspect dependent RCS
- Complex Scattering Matrix

§ Interference (C/No+I, J/S)

- Clutter
- Noise
- Jammers

Enable Search/Track mode Mode: Fixed PRF							
Mode: Fixed PRF							
		Derived Values	1				
PBF -	1kHz 📼	Unambiguous Range:	149.896 km	Ţ.			
		Unambiguous Velocity:	0.025 km/sec	Ţ			
Pulse Width 👻	1e-00/sec	Duty Factor:	0.0001	W			
Probability of Detection							
Probability of False Alarm: 1.00	00e-004						
CFAR Reference Cells: 6							
Pulse Integration							
Analysis Mode: Goal SNR		👻 16 dB 🕎					
Perfect Integrator	Maximum Pu	ilses: 512					
Constant Efficiency:	1.000						
Exponent on Pulse Number:	1.000						
Integration Gain File:							
Filters							
Main Lobe Clutter (MLC)	Bandwidth: 0 m/s						
	PRF Pulse Width Probability of Detection Probability of False Alarm: 1.0(CFAR Reference Cells: 6 Pulse Integration Analysis Mode: Goal SNR Perfect Integrator Constant Efficiency: Exponent on Pulse Number: Integration Gain File: Filters Main Lobe Clutter (MLC)	PRF IKHZ Pulse Width Ie-007 sec Probability of Detection Probability of False Alarm: 1.000e-004 CFAR Reference Cells: 6 Pulse Integration Analysis Mode: Qualse Integration Maximum Pu Constant Efficiency: 1.000 Exponent on Pulse Number: 1.000 Integration Gain File: Integration Gain File:	PRF IKHZ Image: Construction of the second sec	PHF IKHZ Imambiguous Velocity: 0.025 km/sec Pulse Width Ie-007 sec Duty Factor: 0.0001 Probability of Detection Duty Factor: 0.0001 Probability of False Alam: 1.000e-004 Imambiguous Velocity: 0.025 km/sec Pulse Width Imambiguous Velocity: 0.0001 0.0001 Probability of Detection Imambiguous Velocity: 0.0001 Probability of False Alam: 1.000e-004 Imambiguous Velocity: 0.0001 CFAR Reference Cells: 6 Imambiguous Velocity: 0.0001 Pulse Integration Maximum Pulses: 512 Imambiguous Velocity: 16 dB Perfect Integrator Maximum Pulses: 512 Imambiguous Velocity: 1000 Integration Gain File: Imambiguous Velocity: 1.000 Imambiguous Velocity: Imambiguous Velocity: Filters Imambiguous Velocity: 1.000 Imambiguous Velocity: Imambiguous Velocity: Integration Gain File: Imambiguous Velocity: Imambiguous Velocity: Imambiguous Velocity: Imambiguous Velocity: Integration Gain File: Imambiguous Velocity: Imambiguous Velocity: </td			

Aircraft RCS Modeling





Route Design / Optimization









Wind Turbines



Wind turbines are continuously growing in size and in numbers

Product/Rotor diameter (m)	V15	V17	V19	V20	V25	V27	V39	V44	V47	V52	V66	V80	V90
Year of installation	1981	1984	1986	1987	1988	1989	1991	1995	1997	2000	1999	2000	2002
Capacity (kW)	55	75	90	100	200	225	500	600	660	850	1750	2000	3000
MWh/year	217	265	301	346	481	647	1304	1581	1947	2530	4705	6768	9152

Wind Turbines



The Vestas V90 is 90 meters (98.4 yds/295 ft) in diameter or 45 meters to the center of the hub.



211 feet 65 meters



Turbines can be an issue because

- Speed of turbine blades closely match that of aircraft.
 (~150-250 mph) exhibiting spectral similarities.
- Radars perceive turbines as false targets and/or a source of noise, thus degrading sensitivity to cancel effect.
- Degradation of sensitivity is so severe it is sufficient to mask actual aircraft.
- Results in radar obscuration at various altitudes above each turbine site, depending on the radar beam width.

AGI Windturbine and Radar Modeling Agi



Turbine Blade Tip Doppler, with Aircraft

Aagi

Facility-RadarFacility-FAA-Sensor-RadarSweep-FAA-Radar-Radar-FAA-To-Satellite-BladeTip1-1-



Zoomed in: Tip Doppler with Aircraft :



Tip Doppler with Aircraft: Wind Effect 🕰 agi

Facility-RadarFacility-FAA-Sensor-RadarSweep-FAA-Radar-Radar-FAA-To-Satellite-BladeTip1-1-



Solar Power Reflectivity Effects

\land agi

- § Sun position
- § Reflector orientation
- § Solar reflection angle
- § Relative position of Asset
- § Determination of Hazard



Solar Power IR Effects

Aagi

- § Sun position
- **§** Reflector orientation
- § Collector temperature
- § IR signature
- **§** Thermal blooming
- § Relative position of Asset





Wind/Radar Customized Solutions

Radar Obstructions - Overview

Aagi

- § Wind turbines in line of sight degrade radar performance
 - Primary wind turbine effects
 - **§** Reduced Sensitivity (Clutter sources)
 - § Screening / Shadowing
 - § False Targets (Doppler spectrum)
- § Radar Advanced Processing Plugin (RAPP) capabilities
 - Spatial / Temporal and RF Environment
 - § Radar, target, and turbine location/orientation
 - Dwell/pulse, RCS, nacelle/blade relationship
 - § Atmospheric propagation and refraction
 - § Terrain masking and diffraction
 - Land Clutter: Billingsley Surface Clutter Model
 - § Various land/surface classifications
 - Turbine Clutter
 - **§** Interferer size, shape, speed (RCS and Doppler)



Usage of the Wind/Radar UI Plugin



- Along routes: Performs a flight path analysis along a specific route.
- Over areas: Performs an area analysis in a circular grid surrounding a radar at a defined altitude.

§ Measurable Results

- Probability of detection
- Turbine interference power
- Integrated signal power
- Clutter power

§ Supported activities

- Air traffic and defense planning
- Range sustainment
- Wind farm developer planning
- Radar designers/manufacturers/consultants





Radar Advanced Processing Plugin (RAPP)



- § Turbines are modeled as interference sources with a power spectrum.
 - Turbine Blade Length and RPM This determines the tip speed of the turbine blades which affects the width of the Doppler spectrum before accounting for turbine nacelle orientation relative to the radar
 - Turbine Nacelle Orientation This is determined by wind direction and affects the blade orientation relative to the radar.
 - **§** When the turbine disk is normal to the radar line of sight (LOS), there will be no width to the spectrum.
 - **§** When the disk is parallel to the LOS, the radar will see both retreating and advancing blades at the full tip speed, resulting in a spectrum spanning the corresponding Doppler shifts of advancing and retreating tips.
 - Turbine Visibility Terrain may limit visibility of the wind turbine blades.
 - **§** If the top of the turbine disk is below the radar horizon, the disk is excluded from consideration.
 - § If the midpoint of the turbine (the nacelle) is below the radar horizon, the reflected power from the turbine is reduced in half. The spectrum is not modified. This results in a conservative "worst case" calculation
 - Turbine RCS In combination with the incident radar power, this determines the amplitude of the spectrum.

RAPP - Turbine Frequency Spectrum





- The turbine frequency spectrum exhibits constant power over the bandwidth defined by the min/max Doppler of the turbine blade tips.
- In the future, the RAPP will apply blade RCS spectral scaling and aspectdependency, where blade velocity, visibility, and orientation will provide for power variation across the bandwidth

Inputs



Filling an area target and with turbines for a rapid "what if" analysis

Area Target	Propos	ed_Turbines	•
Group	Propose	ed_Turbines	
Turbine Spacing	800	m	
Max Tip Height	136	m 🔻	
Blade Length	45	m 🔹	
Blade Rotation	14	rpm 🔻	Color
Blade RCS	20	dBsm 👻	Add



Inputs



If available, coordinates can be imported via a text (CSV) file.

File				
Group	Existing			
Turbin	e Defaults	(If not pro	ovided by file)	
Max T	ip Height	137	m 🔻	
Blade	Length	46	m •	
Blade	Rotation	14	(pm 🔻	Color
Blade	RCS	20	dBsm 🔻	Add



Turbine Group Identification



Turbines can be grouped for analyses





Area analysis plots around the radar according to the radar's azimuth/range resolutions, propagation loss, and terrain diffraction.





§ User configurable parameters

Radar Site	Radar Sensor1 Radar1							
Turbine Group	<all></all>		•					
Max Range	60	nm 🔻						
Altitude	300	m 🔻 🗚	iL 🔻					
Aircraft RCS	3	m^2 ▼						
Wind Direction	270	deg 🔻 tru	e					
Azimuth Resolution	1.4	deg 👻						





§ Colors ranges of plots are user selectable.

Туре	Probability of Detection		
Min	0.4	unit	
Max	0.9	unit	
Colors	s 3	Terral Terral	Refresh
Po	ints 👿 Mesh 🔲 Values	1	Save Report
Po Area b	iints ☑ Mesh	1	Save Repor





Values optionally displayed upon zooming in close to resolution cells. Note 100% PD (green) in image below, possible currently as ground clutter is not being considered. Future versions will take ground clutter into consideration.





Example scenario is of a small aircraft flying at 300m AGL, exploiting terrain and wind farms to attempt to avoid detection en route to a target in Southwestern PA, USA. Notional data used, including the location of the radar. Radar model is also completely notional.





No color on flight path: Obscured by terrain





Colors on line below are a Propability of Detection (PD) analysis with green being > 90% PD.





PD degredation occurring above turbines. (Generic radar model used.)





View from directly above. (Generic radar model used.)





Area plot and flight path combined.





Points drawn vs. mesh.





Area Analysis Data in CSV Format

the second secon										-
- 21	A	В	с	D	C	Г	G	II	I. I.	1
1	Area Analysis Rep	ort: Radar								
2										
з	Units:									
4	Angle: deg									
5	Distance: nm									
6	Height References	(WGS84)								
7										
8	Radar Coordinate:									
9	Latitude: 10.391									
10	Longitude: 78.959	9								
11	Height (WSS84): 0	.896393088552869	1							
12										
13	Badar Azimuth Be	solution: 1.4								
14	Radar Range Reso	lution: 0.08003748	86609071							
15										
16	Analysis Surface H	leight: 0.32915766	7386609							
17	Analysis Surface II	leight Reference:	AGL							
18										
19	Analysis Results									
50	Fablude	Langitude	Height (W6584)	Azimuth from Ba	Range from Rada	Ground Clutter P	Integrated Signa	l. Noise Power (W)	Probability of De	Single Pulse Sign
21	40.394	-78,9599	0.725550756	0	0.080937489	0	0	0 4.00E-15	0	0
22	40.394	-78.0500	0.725550756	0	0.151874977	0	0	4.00E-15	0	0
23	40.394	AS, 95/99	0.725550756	D	0.242812466	0	0	4.00F 15	a	D
24	40.394	-78.9590	0.725550756	0	0.323740055	0	0	4.00E-15	0	0
522	40.35830055	78,9599	0.708297208	D	0.404687443	0	2.10F 15	4.00F 15	0.001152361	2.10F 15
26	40.40035105	-78,9599	0.097805999	0	0.485624932	0	7.38E-13) 4.00E-15	0.013557585	7.385-15
27	40.40214771	78.9599	0.683345061	0	0.556552421	0	1.64E 16	5 4.00E 15	0.000136054	1.645 16
28	40.40367164	- 78,9599	0.684465569	D	0.647499909	0	1.53E-13	4.00F-15	0.999999.023	12585-18
29	40.40508712	-78.9599	0.694247597	0	0.726437306	0	1.95E-14	4.00E-15	0.149579162	1.950-14
30	40.40655841	78,9599	0.693740062	D	0.809374887	0	1.31F-14	4.00E15	0.056503847	1.31E 14
-31	40,4080387	-78,9599	0.586478358	0	0.800312375	0	2,78E-13) 4.00E-15	1	2.785-13
32	40,40954095	78,9599	0.670418654	0	0.971249854	0	7.78E 16	5 4.00E 15	0.000345145	7.785 16
33	40.41106007	- 78,9599	0.643023239	D	1.052187853	0	1.04E-12	4.00E-15	1	1.045-12
-34	40.41240735	-78,9599	0.628579222	0	1.103124841	0	1.70E-12	4.000-15	1	1.730-12
\mathbb{R}^{n}	40.41384905	78,9599	0.636385798	D	1.21406233	0	1.15E-12	4.00F 15	1	1.15E 12
-36	40.41519715	-78,9599	0.511386034	0	1,201909819	0	7,555-13	4.000-15	1	7.550-13
37	40.41655222	78,9599	0.547766741	0	1.375937307	0	3.34E 13	4.00E 15	1	3.34E 13
38	40.41791353	-78,9599	0.644454606	0	1.456874796	0	4.13F-14	1 4.00F-15	0.642417064	4,135-14
39	40.4193324	-78.0500	0.636085473	0	1.537812285	0	1.70E-20	4.000-15	1.000-04	1.790-20
2013	ALL ACCES (5) 41	an an an	PLA SYNCHOLOGICS		1 6 10 400 4 12		5 100 L 10	a 1976 - 19	ALCOHOLD ALL A	1, 2021, 214



Flight Path Analysis Data in CSV Format

	А	В	С	D	E	F	G	Н	I.	J	К
1	Aircraft Analy	sis Report									
2	Radar: Radar										
3	Aircraft: Aircr	aft									
4											
5	Units:										
6	Angle: deg										
7	Distance: nm										
8	Height Refere	ence: (WGS84)									
9											
10	Radar Coordir	nates									
11	Latitude: 40.3	94									
12	Longitude: -7	8.9599									
13	Height (WGS8	34): 0.39639308	88552856								
14											
15	Radar Azimut	h Resolution:	1.4								
16	Radar Range F	Resolution: 0.0	0809374886609	071							
17											
18	Analysis Resu	Its									
19	Latitude	Longitude	Height (WGS	Azimuth fron	Range from F	Ground Clutt	Integrated Si	Noise Power	Probability o	Single Pulse	Turbine Inter
20	40.62533016	-78.3706226	0.403355865	62.57999993	30.32568504	0	0	0	0	0	0
21	40.62481388	-78.3712329	0.403792961	62.57999993	30.28678286	0	0	0	0	0	0
22	40.62429759	-78.3718433	0.404230057	62.57999993	30.24788803	0	0	0	0	0	0
23	40.6237813	-78.3724536	0.404667153	62.71999993	30.2090006	0	0	0	0	0	0
24	40.62326501	-78.3730639	0.405104249	62.71999993	30.17012059	0	0	0	0	0	0
25	40.62274871	-78.3736742	0.405541345	62.71999993	30.13124803	0	0	0	0	0	0
26	40.62223241	-78.3742845	0.405978441	62.71999993	30.09238294	0	0	0	0	0	0
27	40.62171611	-78.3748948	0.406415537	62.85999993	30.05352537	0	0	0	0	0	0
28	40.6211998	-78.3755051	0.406852633	62.85999993	30.01467532	0	0	0	0	0	0
29	40.62068349	-78.3761154	0.407289729	62.85999993	29.97583285	0	0	0	0	0	0
30	40.62016718	-78.3767257	0.407726824	62.85999993	29.93699796	0	0	0	0	0	0
31	40.61965087	-78.3773359	0.40816392	62.85999993	29.8981707	0	0	0	0	0	0
32	40.61913455	-78.3779462	0.408601016	62.99999993	29.8593511	0	0	0	0	0	0
33	40.61861823	-78.3785564	0.409038111	62.99999993	29.82053918	0	0	0	0	0	0
34	40.6181019	-78.3791666	0.409475207	62.99999993	29.78173497	0	0	0	0	0	0
35	40.61758557	-78.3797768	0.409912303	62.99999993	29.74293851	0	0	0	0	0	0
36	40.61706924	-78.3803871	0.410349398	62.99999993	29.70414982	0	0	0	0	0	0
37	40.61655291	-78.3809973	0.410786493	63.13999993	29.66536893	0	0	0	0	0	0
38	40.61603657	-78.3816074	0.411223589	63.13999993	29.62659588	0	0	0	0	0	0
39	40.61552023	-78.3822176	0.411660684	63.13999993	29.5878307	0	0	0	0	0	0

Availability



- Currently available only with a special pre-release version of STK 10.
- Will be fully available to install without any custom installation upon STK 10.1 release.
- Custom radar models can be built to customer provided specifications.

Future Plans



- Future radar processor models for the RAPP (Radar Advanced Processor Plugin)
- Ability to use aspect-dependent scattering matrix for the blades as opposed to simply scaling magnitude.



NORAD ROEMS



§ Radars modeled

 ARSR-4, ASR-8, ASR-9, ASR-11, CARSR, RYC-8405

§ Application

- STK Engine, CAF, SQL Server
- Requires ROEMS Software Bundle
- Distributable with NORAD permission only. NORAD is generally very willing to share with others (Five Eyes)



NORAD Radar Obstruction Evaluation Modeling System (ROEMS)





DHS WT/RMT Development



- Teamed with Raytheon and Remcom.
- Development started.
- 2 year development program.
- 4d Globe Thin Client Interface.
- Radar systems modeling.
- Ray Path analysis.
- RCS, turbine multi-bounce and multipath.
- Signal process simulators.
- A/C Doppler shift & turbine "clutter".
- Path loss propagation.
- Refraction and diffraction.



